



TABLE I

	CONTROLLER RANGE	CODE VALUE RANGE
ΔR	0 - 100	-50 \rightarrow +50
ΔG	0 - 100	-50 \rightarrow +50
ΔB	0 - 100	-50 \rightarrow +50
ΔL	0 - 100	-50 \rightarrow +50
G	0 - 100	20 \rightarrow 150
C	0 - 100	0 \rightarrow 2

Fig. 2

TABLE II

$$\begin{bmatrix} R' \\ G' \\ B' \end{bmatrix} = \begin{bmatrix} .3086(1-c) + c & .6094(1-c) & .082(1-c) \\ .3086(1-c) & .6094(1-c) + c & .082(1-c) \\ .3086(1-c) & .6094(1-c) & .082(1-c) + c \end{bmatrix} \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$

Fig. 3

TABLE III

$$OUTPUT = \frac{255}{4} \left(\left(1 + \tanh \left[\frac{(INPUT + \Delta L - 128 - G + \Delta R)}{G} \right] \right) + \left(1 + \tanh \left[\frac{(INPUT + \Delta L - 128 + G + \Delta R)}{G} \right] \right) \right)$$

Fig. 4

TABLE IV

$$\left(\frac{255}{4} \right) \left(\left(1 + \tanh \left[\frac{((INPUT - 128) + \beta (INPUT - 128)^3 + \Delta L - G + \Delta R)}{G} \right] \right) + \left(1 + \tanh \left[\frac{((INPUT - 128) + \beta (INPUT - 128)^3 + \Delta L + G + \Delta R)}{G} \right] \right) \right)$$

Fig. 5